

<b>DTC</b>	<b>U0073/94</b>	<b>Control Module Communication Bus OFF</b>
<b>DTC</b>	<b>U0100/65</b>	<b>Lost Communication with ECM / PCM</b>
<b>DTC</b>	<b>U0123/62</b>	<b>Lost Communication with Yaw Rate Sensor Module</b>
<b>DTC</b>	<b>U0124/95</b>	<b>Lost Communication with Lateral Acceleration Sensor Module</b>
<b>DTC</b>	<b>U0126/63</b>	<b>Lost Communication with Steering Angle Sensor Module</b>

**DESCRIPTION**

<b>DTC No.</b>	<b>DTC Detecting Conditions</b>	<b>Trouble Area</b>
U0073/94	When either of following conditions (1 or 2) detected: 1. After data output from skid control ECU completed, output continues for 5 seconds or more. 2. Bus off condition occurs once or more per 0.1 seconds 10 times in succession.	CAN communication system
U100/65	When IG1 terminal voltage 10 V or more and vehicle speed 9 mph (15 km/h) or more, either of following conditions (1 or 2) occurs 10 times in succession: 1. Data cannot be sent to ECM once or more within 5 seconds. 2. Data from ECM cannot be received once or more within 5 seconds.	CAN communication system
U0123/62	When IG1 terminal voltage 10 V or more, either of following conditions (1 or 2) detected: 1. Data from yaw rate sensor cannot be received for 1 second or more. 2. Data from yaw rate sensor cannot be received once or more within 5 seconds.	CAN communication system
U0124/95	When IG1 terminal voltage 9.5 V or more, either of following conditions (1 or 2) detected: 1. Data from deceleration sensor cannot be received for 1 second or more. 2. Data from deceleration sensor cannot be received once or more within 5 seconds.	CAN communication system
U0123/63	When IG1 terminal voltage 10 V or more, either of following conditions (1 or 2) detected: 1. Data from steering angle sensor cannot be received for 1 second or more. 2. Data from steering angle sensor cannot be received once or more within 5 seconds.	CAN communication system

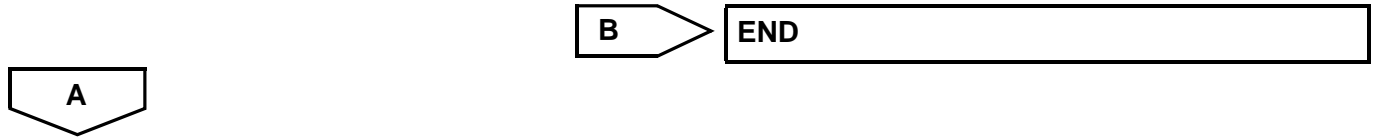
**INSPECTION PROCEDURE**

<b>1</b>	<b>RECONFIRM DTC</b>
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- (a) Clear the DTC(s) (See page [BC-45](#)).
- (b) Check if the same DTC(s) is output (See page [BC-45](#)).

**Result**

Result	Proceed to
DTC output	A
DTC not output	B



**BC**

**REPAIR CAN COMMUNICATION SYSTEM**